



12mm DC Gearmotor - 24mm Type  
Shown on 6mm Isometric Grid



## Product Data Sheet Micro Spur™

### 12mm DC Gearmotor - 24mm Type

**Model: 212-106**

## Ordering Information

The model number 212-106 fully defines the model, variant and additional features of the product. Please quote this number when ordering.  
For stocked types, testing and evaluation samples can be ordered directly through our online store.

## Datasheet Versions

It is our intention to provide our customers with the best information available to ensure the successful integration between our products and your application. Therefore, our publications will be updated and enhanced as improvements to the data and product updates are introduced.

To obtain the most up-to-date version of this datasheet, please visit our website at:

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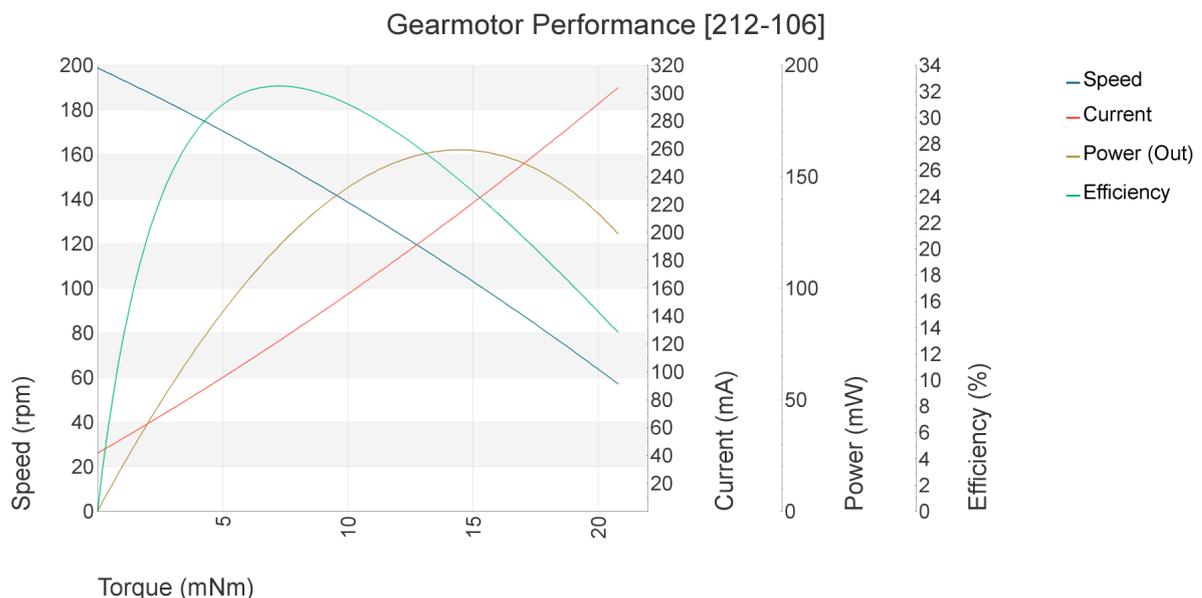
The version number of this datasheet can be found on the bottom left hand corner of any page of the datasheet and is referenced with an ascending R-number (e.g. R002 is newer than R001). Please contact us if you require a copy of the engineering change notice between revisions.

If you have any questions, suggestions or comments regarding this publication or need technical assistance, please contact us via email at: [enquiries@precisionmicrodrives.com](mailto:enquiries@precisionmicrodrives.com) or call us on +44 (0) 1932 252 482

## Key Features

Body Diameter:	12 mm [+/- 0.2]
Body Length:	24 mm [+/- 0.4]
Shaft Orientation:	Inline
Gear Ratio:	50.0 :1
Gearhead Type:	Spur
Rated Operating Voltage:	3 V
Rated Load:	5 mNm
Rated Load Speed:	167 rpm [+/- 23]
Typical Max. Output Power:	158 mW

## Typical DC Gearmotor Performance Characteristics



## Understanding Precision Microdrives Specification and Production Stages

Precision Microdrives Specification Stages				
<p>Precision Microdrives is run on processes and we guide all customers through sets of predefined specification stages as they move from prototype to production. These are designed to allow the flexibility to iterate designs with the eventual certainty required for production parts.</p>				
Base	Sampling	Pre-Production	Production	EOL
<p>Used for factory downselection</p> <p>Typically 0 units</p>	<p>Used for validating prototypes</p> <p>Typically ~ 10 units</p>	<p>Used for validating initial production</p> <p>Typically ~ 1k units</p>	<p>Used for validating mass production</p> <p>Typically &gt;5k+ units</p>	<p>Used as basis for product replacement 'Base' spec</p> <p>Typically 0 units</p>

## Precision Microdrives Capabilities and Competences

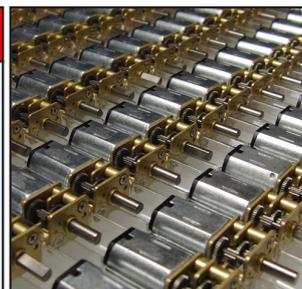
Precision Motor Testing and Motor Testing Services
<p>When we started PMD there were no commercial testing machines available, so we built our own. Ever since we've continued to develop new motor testing machines &amp; procedures each year. Fast forward to today and we now have the most extensive testing facilities in the world for sub 40mm diameter motors, gear motors and vibration motors. These are used to validate motors through specification stages and during manufacturing. We also test motors as a service, provide easy to read reports and assist customers with their interpretation.</p>



Motor Customisation, Design, and Manufacturing
<p>To be useful motors need to be integrated with other parts, such as housings or couplings. We routinely develop and produce complete assemblies, from motors with customised leads or connectors to complete electromechanical mechanisms and integrated control electronics. We will support and guide you through the specification stages from prototype to signing-off for mass production.</p>



Competent and Dependable Supply Chains for Production
<p>Most of the worlds miniature motors are made in Asia, and you need engineers on the factory floor who can maintain the Western values of "doing things right" whilst supporting the Asian values of "getting things done". As a customer you are supported by expert eyes, right at the heart of the manufacturing process where it is needed: On the ground in the UK, Hong Kong, and China.</p>



Quality Engineers on the Ground and Local Engineering Teams
<p>The nature of our business is to confidently produce and supply motors 'On time &amp; To spec'. Our customers benefit from our certified ISO 9001 quality systems, reliable motor production infrastructure, and experience. We have a core competence in helping customers design out over-specified and expensive European drives, with more cost-effective, adequately specified, and verified Asian alternatives.</p>



## Physical Specification

PARAMETER	CONDITIONS	SPECIFICATION
Body Diameter	Max body diameter or max face dimension where non-circular	12 mm [+/- 0.2]
Body Length	Excl. shafts, leads and terminals	24 mm [+/- 0.4]
Unit Weight		9.3 g
No. of Output Shafts		1
Shaft Diameter		3 mm [+ 0 /- 0.03]
Shaft Orientation		Inline
Shaft Length	Measured from motor body face	10 mm [+/- 0.3]

## Construction Specification

PARAMETER	CONDITIONS	SPECIFICATION
Motor Construction		Iron Core
Gear Ratio		50.0 :1
Gearhead Type		Spur
Commutation		Precious Metal Brush
Rotation Direction	As viewed from the primary shaft end / or motor top	CCW
No. of Poles		3
Bearing Type		Sintered Bronze

## Operational Specification

PARAMETER	CONDITIONS	SPECIFICATION
Rated Operating Voltage		3 V
Rated Load	Maximum continuous torque	5 mNm
Rated Load Speed	At rated voltage under fixed torque at rated load	167 rpm [+/- 23]
N/L Speed	Measured at rated voltage	197 rpm [+/- 24]
Max. Start Voltage	Measured at no load	1 V
Max. N/L Current	Measured at rated voltage	63 mA
Max. Operating Voltage		3.6 V
Max. Stall Current	Momentary stall condition current at rated voltage	460 mA
Max. Rated Load Current	At rated voltage under fixed torque at rated load	139 mA
Min. Insulation Resistance	At 50V DC between motor terminal and case	1 MOhm

Important: The characteristics of the motor is the typical operating parameters of the product. The data herein offers design guidance information only and supplied batches are validated for conformity against the specifications on the previous page.

### Typical Performance Characteristics

PARAMETER	CONDITIONS	SPECIFICATION
Typical Rated Load Power Consumption	At rated voltage and load	297 mW
Typical N/L Current	At rated voltage	40 mA
Typical Peak Efficiency		31.2 %
Typical Start Current	At rated voltage	425 mA
Typical Peak Eff. Torque		7.4 mN·m
Typical Peak Eff. Speed		152 rpm
Typical Peak Eff. Current		127 mA
Typical Peak Eff. Power Out	Power consumption at rated voltage	118 mW
Typical Max. Output Power		158 mW
Typical Terminal Resistance		7 Ohm
Typical Terminal Inductance		1,284 uH

### Typical Durability Characteristics

PARAMETER	CONDITIONS	SPECIFICATION
Max. Axial Compression		45 N
Max. Radial Load		4,000 mN
Typical Max. Mech. Noise		60 dB(A)

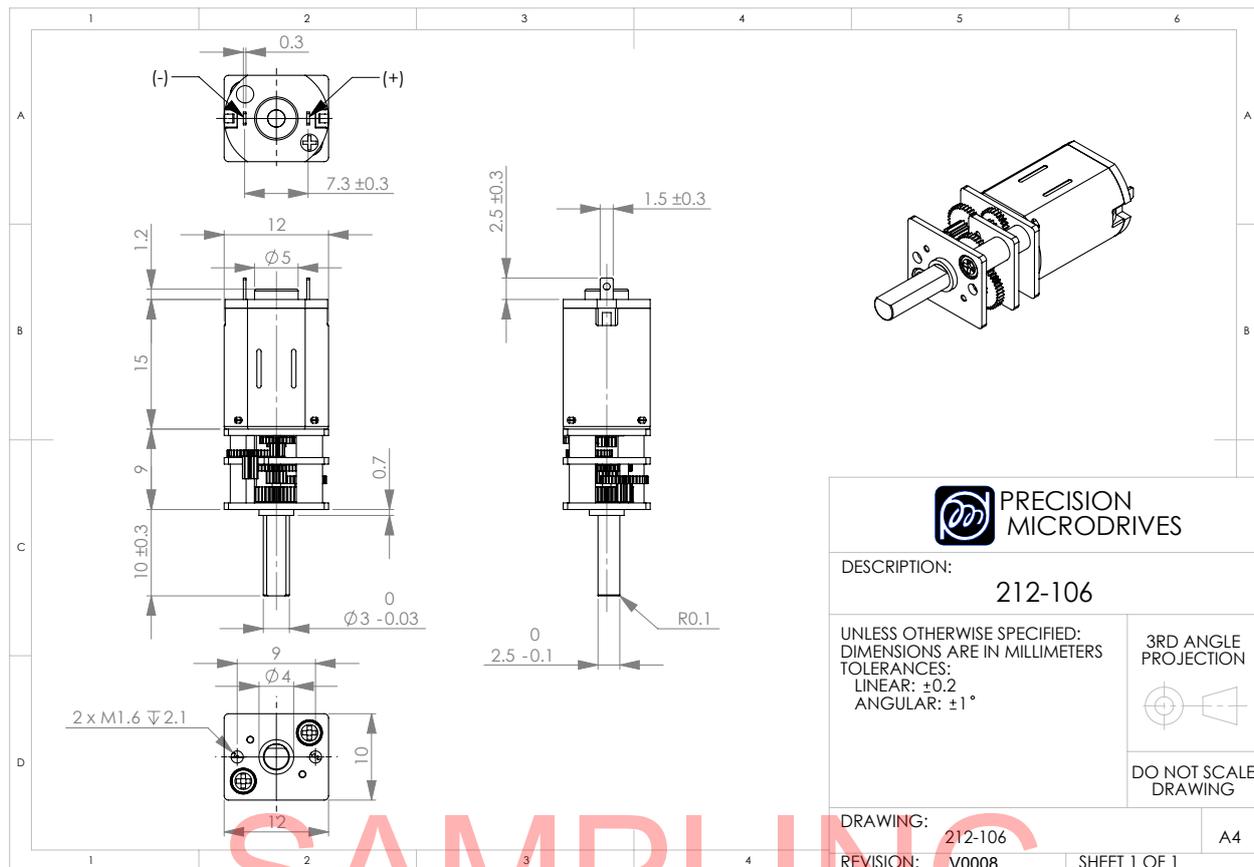
### Environmental Characteristics

PARAMETER	CONDITIONS	SPECIFICATION
Max. Operating Temp.		50 Deg.C
Min. Operating Temp.		-10 Deg.C
Max. Storage & Transportation Temp.		80 Deg.C
Min. Storage & Transportation Temp.		-40 Deg.C

### Typical Packing Conditions

PARAMETER	CONDITIONS	SPECIFICATION
Carton Type		Boxed Trays

## Product Dimensional Specification



## Life Support Policy

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As used herein:

1. Life support devices or systems are devices or systems which, (a) are intended for surgical implant into the body, or (b) support or sustain life, and whose failure to perform when properly used in accordance with instructions for use provided in the labeling, can be reasonably expected to result in a significant injury to the user.
2. A critical component is any component of a life support device or system whose failure to perform can be reasonably expected to cause the failure of the life support device or system, or to affect its safety or effectiveness.



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