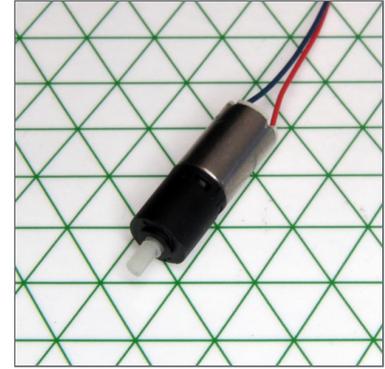


Product Data Sheet

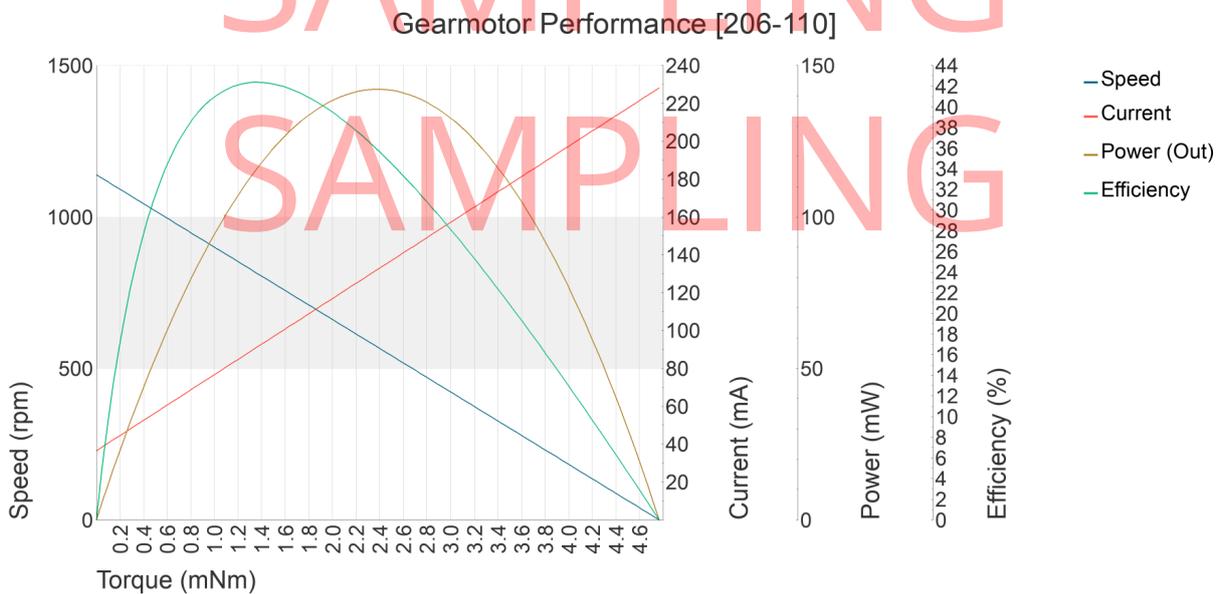
Range: Nano Planetary
 Title: 6mm DC Gearmotor
 Type: Undefined
 Model: 206-110

6mm DC Gearmotor
 16mm Type
 Shown on 6mm Isometric Grid



KEY FEATURES	
Body Diameter	6 mm [+/- 0.1]
Body Length	16.3 mm [+/- 0.2]
Shaft Orientation	Inline
Gear Ratio	25.0 :1
Gearhead Type	Planetary
Rated Operating Voltage	3 V
Rated Load	1 mNm
Rated Load Speed	840 rpm [+/- 150]
Typical Max. Output Power	107 mW

TYPICAL DC MOTOR PERFORMANCE CHARACTERISTICS



ORDERING INFORMATION

The model number fully defines the model, variant and additional features of the product. Please quote this number when ordering. For stocked types, testing and evaluation samples can be ordered directly through our online store.

FIND OUT HOW THIS PART COULD MEET YOUR SPECIFICATIONS

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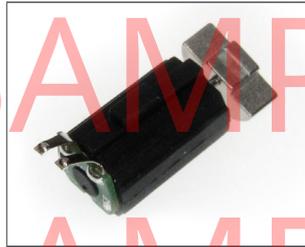
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DESIGN FOR APPLICATION CASE STUDIES



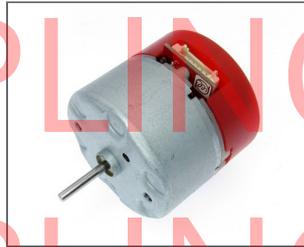
ENCAPSULATED VIBRATION MOTOR FOR A CPR TRAINING DUMMY

- Low volume, high value manufacturing
- Custom CNC machined enclosure
- Optimised haptic performance
- Custom PCB including EMI filters
- Part no. 334-401.001



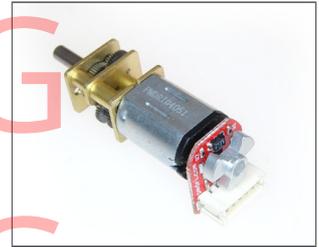
VIBRATION MOTOR HIGHLY OPTIMISED FOR RUGGEDISED FIRE AND POLICE EMERGENCY RADIOS

- High volume production
- Optimised for emergency services application
- Ruggedised design with custom rubber 'suspension' cover
- Custom PCB with spring legs for simplified production assembly times
- Part no. 308-104.001



PRECISION SPEED AND TORQUE CONTROLLED SERVO WITH INTEGRATED TUNABLE PID LOOP FOR SINGLE-USE SCIENTIFIC INSTRUMENT.

- Medium volume, high value assembly
- Proprietary PID controller converts cost-effective motor design into a precision servo
- Adapted control software including digital IO (to customer's specification)
- Part no. 132-100.001



CUSTOMISED PRECISION GEAR MOTOR WITH ROBUST OPTICAL ENCODER

- High volume production
- Application specific output shaft
- Tailored motor performance curves
- Rear motor shaft with noise resistant optical encoder
- Part no. 212-116.001

PHYSICAL SPECIFICATION

PARAMETER	CONDITIONS	SPECIFICATION
Body Diameter	Max body diameter or max face dimension where non-circular	6 mm [+/- 0.1]
Body Length	Excl. shafts, leads and terminals	16.3 mm [+/- 0.2]
Unit Weight		1.2 g
No. of Output Shafts		1
Shaft Diameter		2 mm [+ 0 /- 0.05]
Shaft Length	Measured from motor body face	3.6 mm [+/- 0.2]
Shaft Orientation		Inline

CONSTRUCTION SPECIFICATION

PARAMETER	CONDITIONS	SPECIFICATION
Motor Construction		Coreless
Gear Ratio		25.0 :1
Gearhead Type		Planetary
Commutation		Precious Metal Brush
Rotation Direction	As viewed from the primary shaft end / or motor top	CW
No. of Poles		3
Bearing Type		Sintered Bronze

LEADS & CONNECTORS SPECIFICATION

PARAMETER	CONDITIONS	SPECIFICATION
Lead Length	Lead lengths defined as total length or between motor and connector	100 mm [+/- 5]
Lead Strip Length		1.5 mm [+/- 0.5]
Lead Wire Gauge		32 AWG
Lead Configuration		Straight

FIND OUT HOW THIS PART COULD MEET YOUR SPECIFICATIONS

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Call: +44 (0) 1932 252482

OPERATIONAL SPECIFICATION

PARAMETER	CONDITIONS	SPECIFICATION
Rated Operating Voltage		3 V
Rated Load	Maximum continuous torque	1 mNm
Rated Load Speed	At rated voltage under fixed torque at rated load	840 rpm [+/- 150]
N/L Speed	Measured at rated voltage	1,200 rpm [+/- 150]
Max. Start Voltage	Measured at no load	1 V
Max. N/L Current	Measured at rated voltage	50 mA
Max. Operating Voltage		3.6 V
Max. Start Current	At rated voltage	271 mA
Max. Rated Load Current	At rated voltage under fixed torque at rated load	115 mA
Min. Insulation Resistance	At 50V DC between motor terminal and case	1 MOhm

Important: The characteristics of the motor is the typical operating parameters of the product. The data herein offers design guidance information only and supplied batches are validated for conformity against the specifications on the previous page.

TYPICAL PERFORMANCE CHARACTERISTICS

PARAMETER	CONDITIONS	SPECIFICATION
Typical Rated Load Power Consumption	At rated voltage and load	245 mW
Typical N/L Current	At rated voltage	29 mA
Typical Peak Efficiency		36 %
Typical Start Current	At rated voltage	210 mA
Typical Peak Eff. Torque		0.91 mN·m
Typical Peak Eff. Speed		877 rpm
Typical Peak Eff. Current		76 mA
Typical Peak Eff. Power Out	Power out at rated voltage at the peak efficiency torque point	83 mW
Typical Max. Output Power		107 mW
Typical Terminal Resistance		13.3 Ohm
Typical Terminal Inductance		58 uH

ENVIRONMENTAL CHARACTERISTICS

PARAMETER	CONDITIONS	SPECIFICATION
Max. Operating Temp.		60 Deg.C
Min. Operating Temp.		-10 Deg.C
Max. Storage & Transportation Temp.		70 Deg.C
Min. Storage & Transportation Temp.		-20 Deg.C

FIND OUT HOW THIS PART COULD MEET YOUR SPECIFICATIONS

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TYPICAL PACKING CONDITIONS

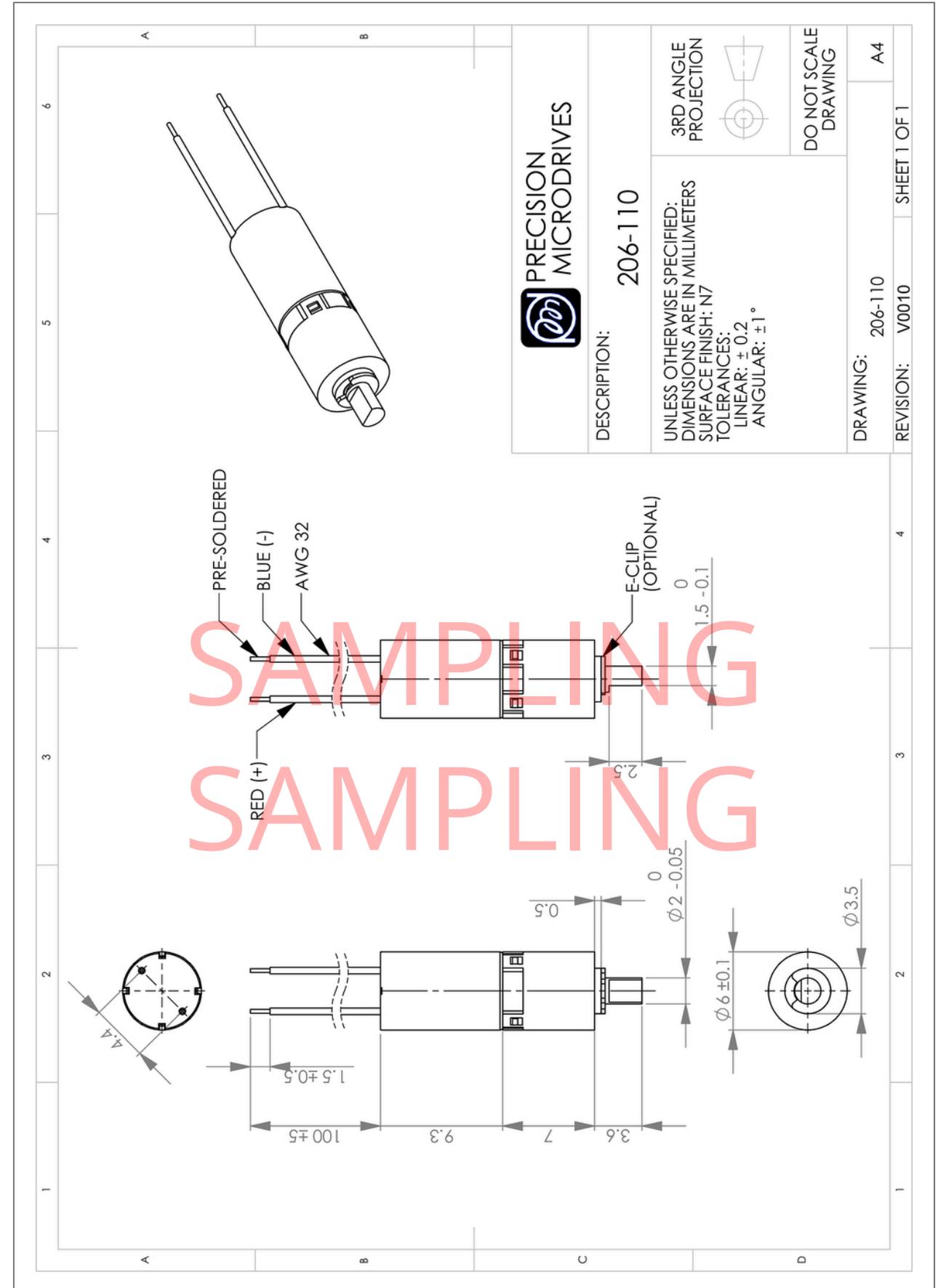
PARAMETER	CONDITIONS	SPECIFICATION
Carton Type		Boxed Trays

SAMPLING SAMPLING

FIND OUT HOW THIS PART COULD MEET YOUR SPECIFICATIONS

Email: enquiries@precisionmicrodrives.com
Call: +44 (0) 1932 252482

PRODUCT DIMENSIONAL SPECIFICATION



FIND OUT HOW THIS PART COULD MEET YOUR SPECIFICATIONS

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 Call: +44 (0) 1932 252482

HOW TO ORDER

Call or email us with your order requirements at:

Email: enquiries@precisionmicrodrives.com

Phone: **+44 (0) 1932 252482**

Please quote the full part number when ordering or making an enquiry. Some products can be ordered in smaller volumes directly from our website: www.precisionmicrodrives.com

DATASHEET REVISION AND VERSION NUMBERING

We aim to provide our customer with the most detailed product information available. Sometimes changes are necessary, and these will be controlled by our engineering change request and notification process. To track datasheet versions we use both a 'production revision number' and a 'document version number'. These can be found at the bottom of every page. In some cases, such as documentation errors, the document version number can increase without triggering a product revision.

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1. Life support devices or systems are devices or systems which,
 - 1.1. are intended for surgical implant into the body, or
 - 1.2. support or sustain life, and whose failure to perform when properly used in accordance with instructions for use provided in the labeling, can be reasonably expected to result in a significant injury to the user or a third party.
2. A critical component is any component of a life support device or any other system or machine whose failure to perform can be reasonably expected to cause the failure of the life support device or system, or to affect its safety or effectiveness.

BATCH NUMBERING, MANUFACTURING, TRACEABILITY AND LABELLING

Every part manufactured by Precision Microdrives is at minimum identified and traced via a batch number. Where physically practical, we try to make each part with a batch number. In addition, some parts carry a lot code or barcode serial numbers. If traceability is a core requirement for your purchase, let us know and we'll outline the production options for you.

STANDARD QUALITY CONTROLS AND ISO 9001

Precision quality control is one of our 3 key competitive advantages. All motors that we produce undergo 100% line inspection followed by strict and detailed batch sample testing in accordance with ISO 2859. All of the processes operated at Precision Microdrives are managed within our ISO 9001 quality system.



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